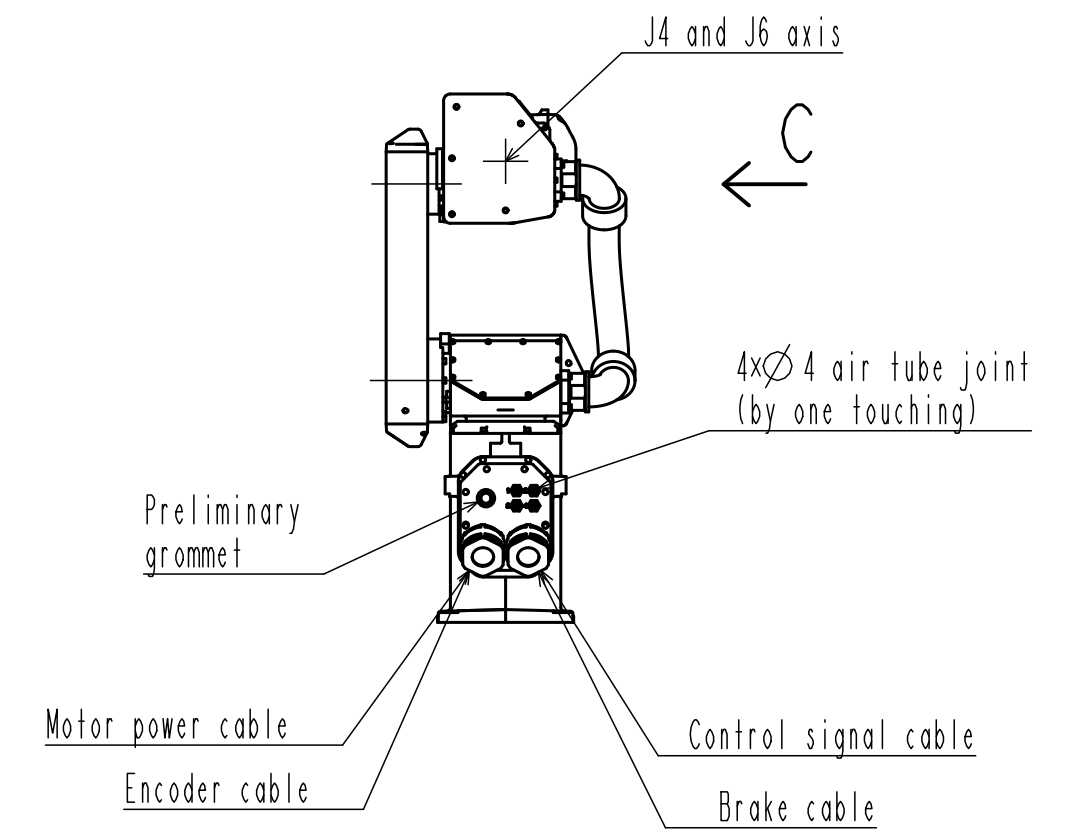
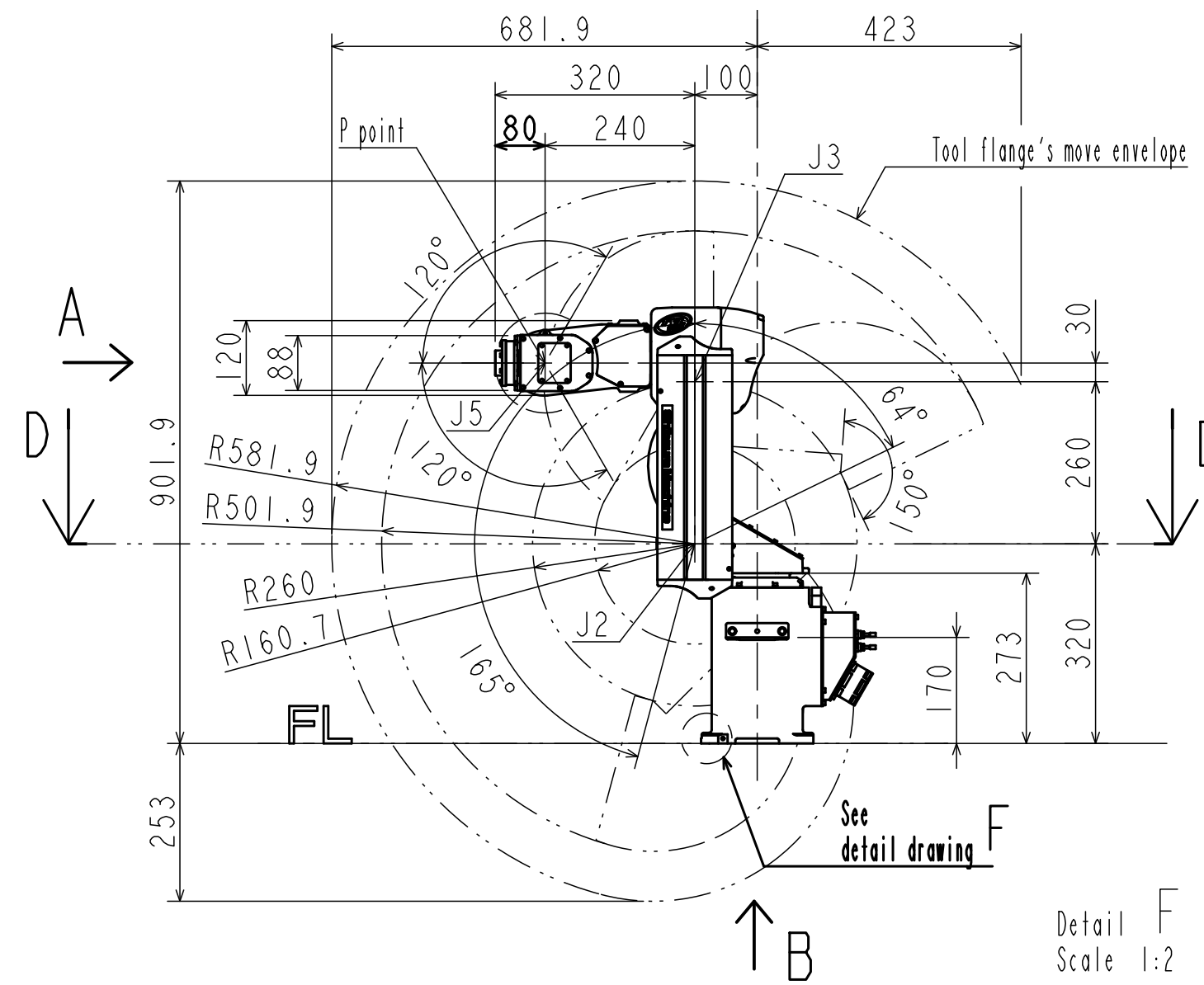
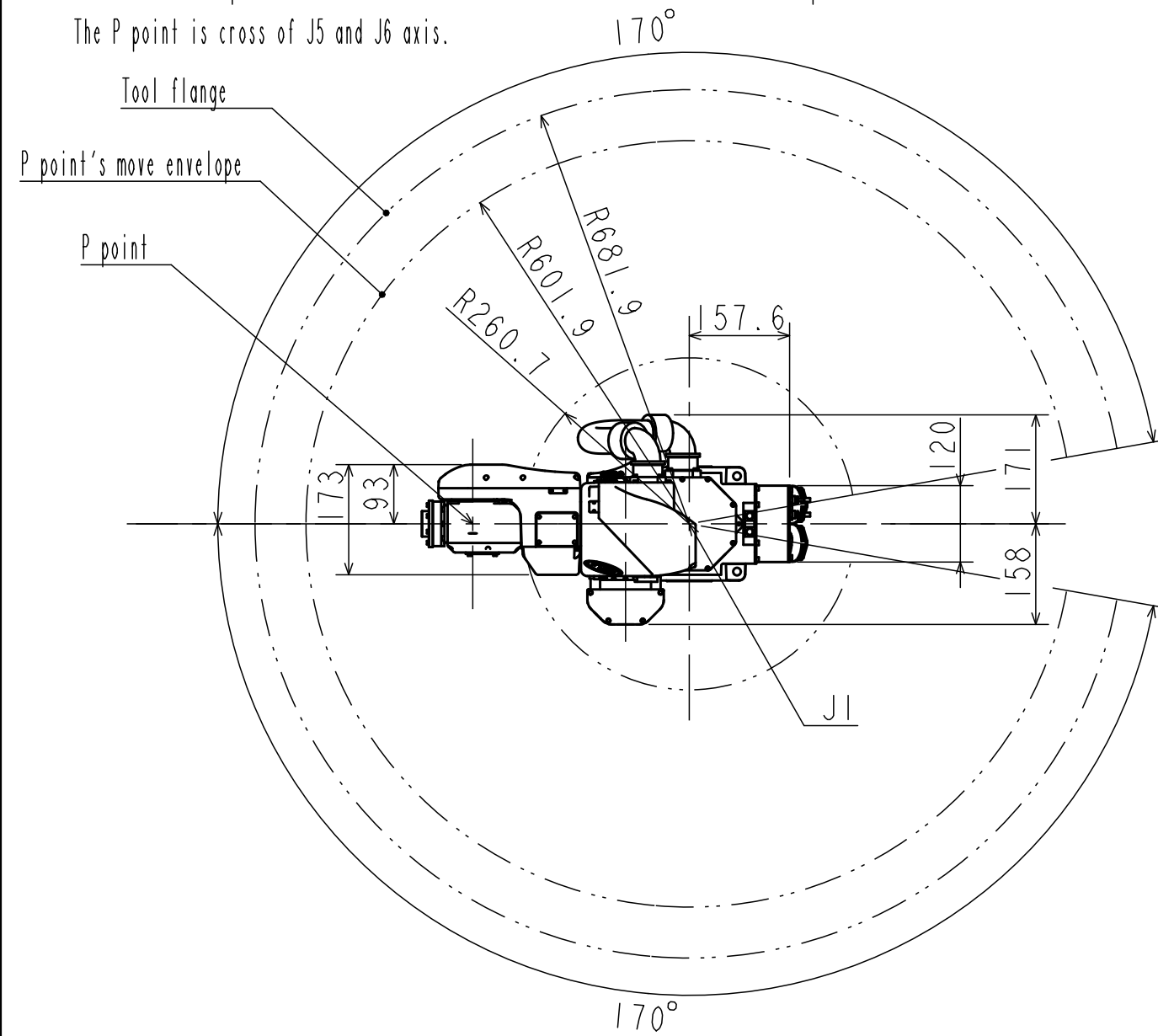
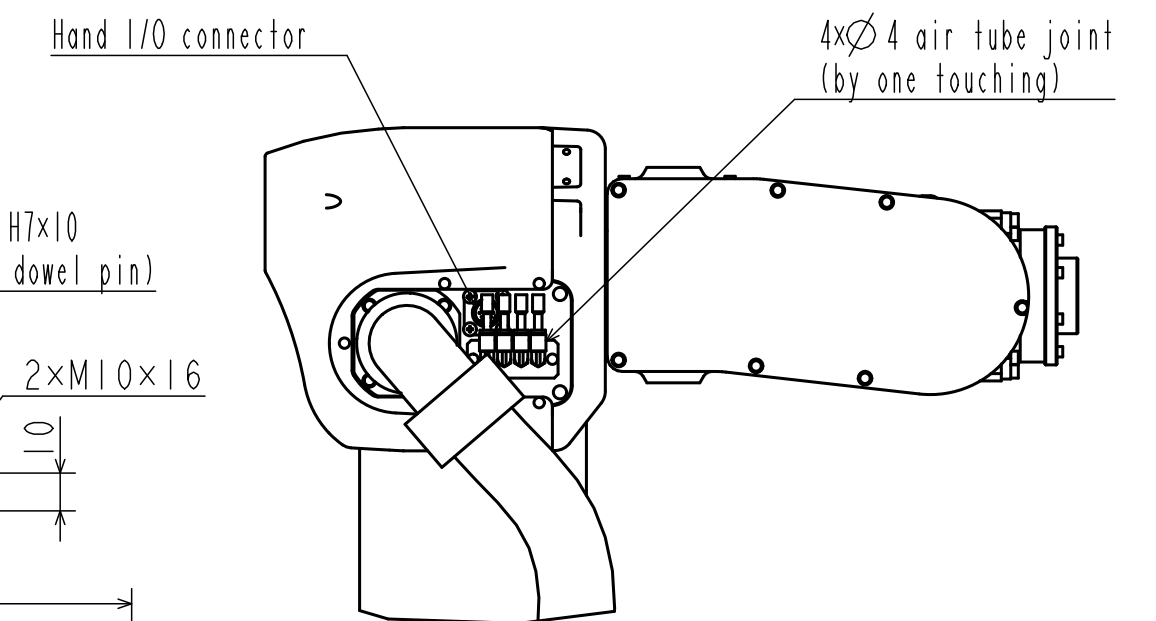


The P point's move envelope

The P point is cross of J5 and J6 axis.



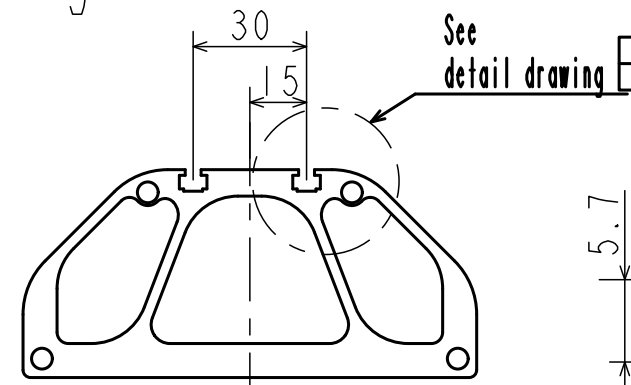
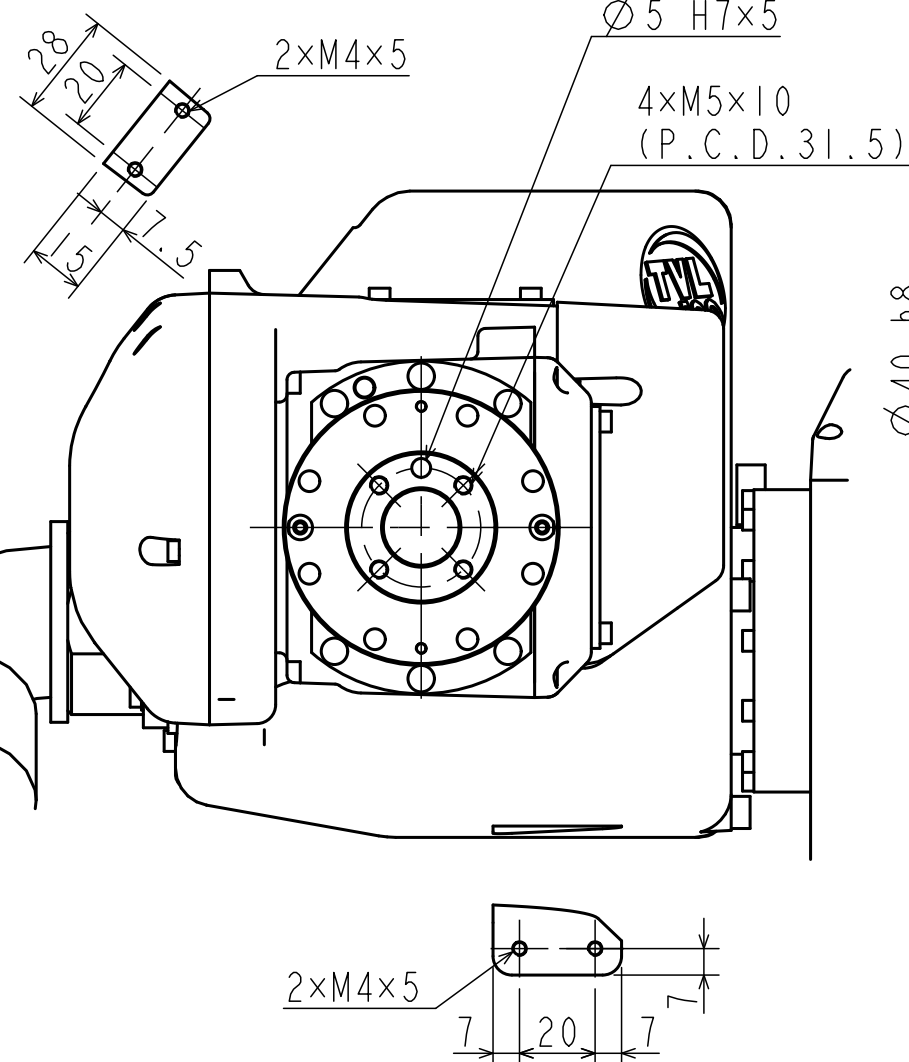
View C (Scale 1:4)



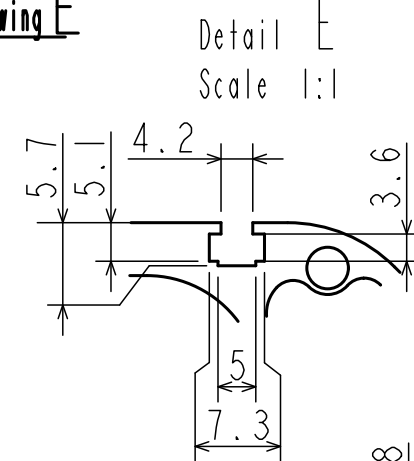
T-groove dimension

Detail of tool flange

View A (Scale 1:2)



Detail D-D Scale 1:2

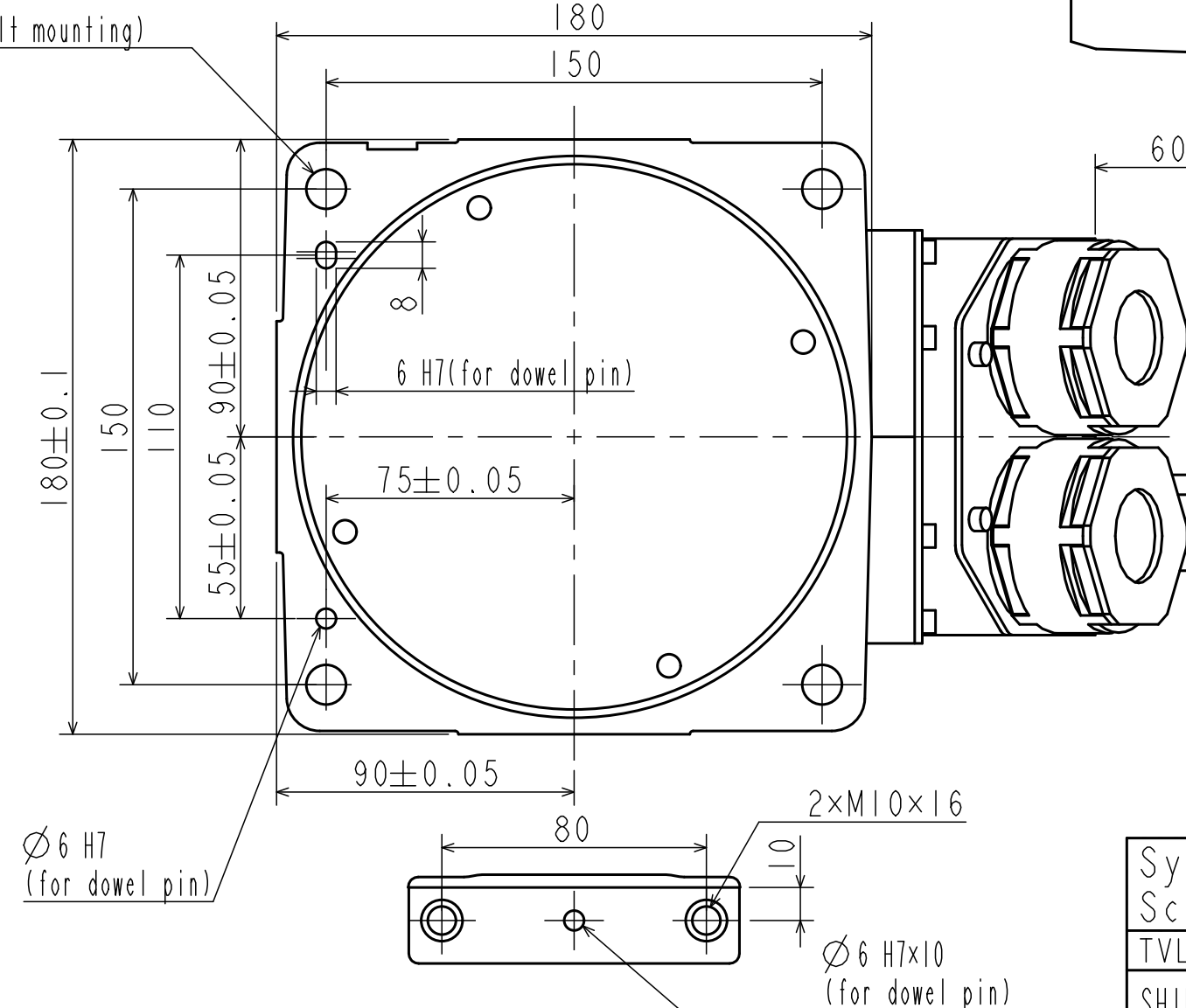


Detail E Scale 1:1

Detail of base fixture

View B (Scale 1:2)

4x12 holes (for M10 bolt mounting)



Joint	Moving envelope(deg)
J1	±170
J2	-64~+165
J3	0~+150
J4	±190
J5	±120
J6	±360

The orientation in this drawing is 90° for J3 only and 0° for other axes.

System Robot Outline
Scale 1:10

TVL500

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